

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	2	"20070112466".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/05 19:20
S2	20	("4615515" "6886061" "4235218" "4262454" "4235218" "4262454" "5897114" "5927936" "5836577" "5813825" "5996993" "6161995"). pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:18
S3	1640	keio.as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:20
S4	411	700/3.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:21
S5	1	(kouhei with ohnishi).as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:22
S6	1	(masaki with kitajima). as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:22
S7	7	(kouhei with ohnishi).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:22
S8	23	(masaki with kitajima). in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23

S9	8	(yasuhide with morikawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23
S10	43729	(souji ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23
S11	1	(souji with ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23
S12	550	(toshiharu with furukawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:24
S13	295	(toshiyuki with murakami).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:25
S14	70	(kazuo with nakazawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:25
S15	110	(wataru with iida).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:25
S16	3	(tomoko with yano).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:26
S17	2247	(position with force with driv\$4 with control).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:27
S18	55	(position with force with driv\$4 with control with acceleration).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:27

S19	58645	reaction adj force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:28
S20	199	S17 and S19	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:28
S21	412	(position with force with driv\$4 with control with signal).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:29
S22	5	S21 and master and slave	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:30
S23	8464	(700/3,260,2,19-21,28- 46,54-61,302).ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:43
S24	426	(inverted adj pendulum) and control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:21
S25	209	S24 and force and acceleration	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22
S26	0	S25 and (lab adj view)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22
S27	0	S24 and (lab adj view)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22
S28	116	S24 and (state with control)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22

S29	78	S25 and S28	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:23
S30	36	S29 and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:23
S31	37	(inverted adj pendulum). TL	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:38
S32	161	(inverted adj pendulum) and ROD	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:52
S33	271	(inverted adj pendulum) and balanc53	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:20
S34	27	(inverted adj pendulum) and balanc53 and (control adj theory)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:20
S35	0	gripper and (bilateral adj control) and acceleration and position and (control adj theory) and (reaction and force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:43
S36	11	gripper and (bilateral adj control) and acceleration and position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:43
S37	0	gripper and (bilateral adj control) and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:47
S38	1	gripper and (bilateral adj control) and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:47

S39	55	gripper and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:48
S40	3	gripper and acceleration and position and (reaction adj force) and gain and (natural adj frequency)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:48
S41	1	forceps and acceleration and position and (reaction adj force) and gain and (natural adj frequency)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:18
S42	10	forceps and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:19
S43	212	forceps and acceleration and position and control and motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:21
S44	169	forceps and acceleration and position and control and motor and force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:21
S45	134	forceps and acceleration and position and control and motor and force and frequencS4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:22
S46	38	forceps and acceleration and position and control and motor and force and frequencS4 and bilateral	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:22
S47	1	(reaction adj force) and observer and master and slave and acceleration and position and control and motor and force and frequencS4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:29

S48	2	observer and master and slave and acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:29
S49	13	observer and acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:30
S50	70	acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:31
S51	57	S50 not S49	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:31
S52	11	S51 and (force gripper)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:31
S53	2325	encoder and (host adj computer) and control and position and force and (noise error disturbance)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:38
S54	1883	S53 and (movement friction)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:39
S55	88	S54 and (observer observability) and (sens \$3 detect\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:40
S56	2	"20070112466".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47

S57	20	("4615515" "6886061" "4235218" "4262454" "4235218" "4262454" "5897114" "5927936" "5836577" "5813825" "5996993" "6161995"). pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S58	1640	keio.as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S59	411	700/3.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S60	1	(kouhei with ohnishi).as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S61	1	(masaki with kitajima). as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S62	7	(kouhei with ohnishi).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S63	23	(masaki with kitajima). in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S64	8	(yasuhide with morikawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S65	43729	(souji ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47

S66	1	(souji with ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S67	550	(toshiharu with furukawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S68	295	(toshiyuki with murakami).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S69	70	(kazuo with nakazawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S70	110	(wataru with iida).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S71	3	(tomoko with yano).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S72	2247	(position with force with driv\$4 with control).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S73	55	(position with force with driv\$4 with control with acceleration).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S74	58645	reaction adj force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S75	199	S72 and S74	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47

S76	412	(position with force with driv\$4 with control with signal).cflm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S77	5	S76 and master and slave	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S78	8464	(700/3,260,2,19-21,28-46,54-61,302).ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S79	411	S59 and S78	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:51
S80	8464	S59 S78	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:51
S81	556	S80 and force and acceleration	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:51
S82	1	S49 and S80	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:52
S83	377	S81 and position and control and motor and force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:53
S84	1	S39 and (bilateral adj control)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:53
S85	55	S39 and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:53

S86	9	("6860160" "7234729" "6728616" "6849807" "6705345").pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 22:56
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2/28/2008 7:19:52 PM

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